

MATRICES AND DETERMINANTS

Matrices :

- An $m \times n$ matrix is a rectangular array of mn numbers (real or complex) arranged in an ordered set of m horizontal lines called rows and n vertical lines called columns enclosed in parentheses. An $m \times n$ matrix A is usually written as :

$$A = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1j} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2j} & \dots & a_{2n} \\ \vdots & \vdots & & & & \\ a_{i1} & a_{i2} & \dots & a_{ij} & \dots & a_{in} \\ \vdots & \vdots & & & & \\ a_{m1} & a_{m2} & \dots & a_{mj} & \dots & a_{mn} \end{bmatrix}$$

Where $1 \leq i \leq m$ and $1 \leq j \leq n$ and is written in compact form as $A = [a_{ij}]_{m \times n}$

- A matrix $A = [a_{ij}]_{m \times n}$ is called
 - a rectangular matrix if $m \neq n$
 - a square matrix if $m = n$
 - a row matrix or row vector if $m = 1$
 - a column matrix or column vector if $n = 1$
 - a null matrix if $a_{ij} = 0$ for all i, j and is denoted by $O_{m \times n}$
 - a diagonal matrix if $a_{ij} = 0$ for $i \neq j$
 - a scalar matrix if $a_{ij} = 0$ for $i \neq j$ and all diagonal elements a_{ii} are equal
- Two matrices can be added only when they are of same order. If $A = [a_{ij}]_{m \times n}$ and $B = [b_{ij}]_{m \times n}$, then sum of A and B is denoted by $A + B$ and is a matrix $[a_{ij} + b_{ij}]_{m \times n}$
- The product of two matrices A and B , written as AB , is defined in this very order of matrices if number of columns of A (pre factor) is equal to the number of rows of B (post factor). If AB is defined, we say that A and B are conformable for multiplication in the order AB .
If $A = [a_{ij}]_{m \times n}$ and $B = [b_{ij}]_{n \times p}$, then their product AB is a matrix $C = [c_{ij}]_{m \times p}$ where C_{ij} = sum of the products of elements of i th row of A with the corresponding elements of j th column of B .
- Types of matrices :
 - Idempotent if $A^2 = A$
 - Periodic if $A^{k+1} = A$ for some positive integer k . The least value of k is called the period of A .

(iii) Nilpotent if $A^k = O$ when k is a positive integer. Least value of k is called the index of the nilpotent matrix.

(iv) Involutary if $A^2 = I$.

- The matrix obtained from a matrix $A = [a_{ij}]_{m \times n}$ by changing its rows into columns and columns of A into rows is called the transpose of A and is denoted by A' .
- A square matrix $a = [a_{ij}]_{n \times n}$ is said to be
 - Symmetric if $a_{ij} = a_{ji}$ for all i and j i.e. if $A' = A$.
 - Skew-symmetric if $a_{ij} = -a_{ji}$ for all i and j i.e., if $A' = -A$.
- Every square matrix A can be uniquely written as sum of a symmetric and a skew-symmetric matrix.

$$A = \frac{1}{2} (A + A') + \frac{1}{2} (A - A') \text{ where } \frac{1}{2} (A + A') \text{ is symmetric and } \frac{1}{2} (A - A') \text{ is skew-symmetric.}$$

- Let $A = [a_{ij}]_{m \times n}$ be a given matrix. Then the matrix obtained from A by replacing all the elements by their conjugate complex is called the conjugate of the matrix A and is denoted by $\bar{A} = [\bar{a}_{ij}]$.

Properties :

- $\overline{(\bar{A})} = A$
- $\overline{(A + B)} = \bar{A} + \bar{B}$
- $\overline{(\lambda A)} = \bar{\lambda} \bar{A}$, where λ is a scalar
- $\overline{(AB)} = \bar{A} \bar{B}$.

Determinant :

Consider the set of linear equations $a_1x + b_1y = 0$ and $a_2x + b_2y = 0$, where on eliminating x and y we get the eliminant $a_1b_2 - a_2b_1 = 0$; or symbolically, we write in the determinant notation

$$\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix} \equiv a_1b_2 - a_2b_1 = 0$$

Here the scalar $a_1b_2 - a_2b_1$ is said to be the expansion of the 2×2 order determinant $\begin{vmatrix} a_1 & b_1 \\ a_2 & b_2 \end{vmatrix}$ having 2 rows and 2 columns.

Similarly, a determinant of 3×3 order can be expanded as :

$$\begin{vmatrix} a_1 & b_1 & c_1 \\ a_2 & b_2 & c_2 \\ a_3 & b_3 & c_3 \end{vmatrix} = a_1 \begin{vmatrix} b_2 & c_2 \\ b_3 & c_3 \end{vmatrix} - b_1 \begin{vmatrix} a_2 & c_2 \\ a_3 & c_3 \end{vmatrix} + c_1 \begin{vmatrix} a_2 & b_2 \\ a_3 & b_3 \end{vmatrix}$$

$$\begin{aligned} &= a_1(b_2c_3 - b_3c_2) - b_1(a_2c_3 - a_3c_2) + c_1(a_2b_3 - a_3b_2) \\ &= a_1(b_2c_3 - b_3c_2) - a_2(b_1c_3 - b_3c_1) + a_3(b_1c_2 - b_2c_1) \\ &= \sum(\pm a_i b_j c_k) \end{aligned}$$

- To every square matrix $A = [a_{ij}]_{m \times n}$ is associated a number of function called the determinant of A and is denoted by $|A|$ or $\det A$.

$$\text{Thus, } |A| = \begin{vmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{vmatrix}$$

- If $A = [a_{ij}]_{n \times n}$, then the matrix obtained from A after deleting i th row and j th column is called a submatrix of A. The determinant of this submatrix is called a minor or a_{ij} .
- Sum of products of elements of a row (or column) in a \det with their corresponding cofactors is equal to the value of the determinant.

$$\text{i.e., } \sum_{i=1}^n a_{ij} C_{ij} = |A| \text{ and } \sum_{j=1}^n a_{ij} C_{ij} = |A|.$$

- (i) If all the elements of any two rows or two columns of a determinant are either identical or proportional, then the determinant is zero.
- (ii) If A is a square matrix of order n, then $|kA| = k^n |A|$.
- (iii) If Δ is determinant of order n and Δ' is the determinant obtained from Δ by replacing the elements by the corresponding cofactors, then $\Delta' = \Delta^{n-1}$
- (iv) Determinant of a skew-symmetric matrix of odd order is always zero.
- The determinant of a square matrix can be evaluated by expanding from any row or column.
- If $A = [a_{ij}]_{n \times n}$ is a square matrix and C_{ij} is the cofactor of a_{ij} in A, then the transpose of the matrix obtained from A after replacing each element by the corresponding cofactor is called the adjoint of A and is denoted by $\text{adj. } A$.

$$\text{Thus, } \text{adj. } A = [C_{ij}]'$$

Properties of adjoint of a square matrix

- (i) If A is a square matrix of order n, then $A \cdot (\text{adj. } A) = (\text{adj. } A) \cdot A = |A| I_n$.
- (ii) If $|A| = 0$, then $A (\text{adj. } A) = (\text{adj. } A) A = O$.
- (iii) $|\text{adj. } A| = |A|^{n-1}$ if $|A| \neq 0$
- (iv) $\text{adj. } (AB) = (\text{adj. } B) (\text{adj. } A)$.
- (v) $\text{adj. } (\text{adj. } A) = |A|^{n-2} A$.

- Let A be a square matrix of order n. Then the inverse of A is given by $A^{-1} = \frac{1}{|A|} \text{adj. } A$.

- Reversal law : If A, B, C are invertible matrices of same order, then

$$(i) (AB)^{-1} = B^{-1} A^{-1}$$

$$(ii) (ABC)^{-1} = C^{-1} B^{-1} A^{-1}$$

- Criterion of consistency of a system of linear equations

- (i) The non-homogeneous system $AX = B$, $B \neq 0$ has unique solution if $|A| \neq 0$ and the unique solution is given by $X = A^{-1}B$.

- (ii) Cramer's Rule : If $|A| \neq 0$ and $X = (x_1, x_2, \dots, x_n)'$ then for each $i = 1, 2, 3, \dots, n$; $x_i = \frac{|A_i|}{|A|}$ where

A_i is the matrix obtained from A by replacing the i th column with B.

- (iii) If $|A| = 0$ and $(\text{adj. } A) B = O$, then the system $AX = B$ is consistent and has infinitely many solutions.

- (iv) If $|A| = 0$ and $(\text{adj. } A) B \neq O$, then the system $AX = B$ is inconsistent.

- (v) If $|A| \neq 0$ then the homogeneous system $AX = O$ has only null solution or trivial solution

$$(i.e., x_1 = 0, x_2 = 0, \dots, x_n = 0)$$

- (vi) If $|A| = 0$, then the system $AX = O$ has non-null solution.

- (i) Area of a triangle having vertices at (x_1, y_1) , (x_2, y_2)

$$\text{and } (x_3, y_3) \text{ is given by } \frac{1}{2} \begin{vmatrix} x_1 & y_1 & 1 \\ x_2 & y_2 & 1 \\ x_3 & y_3 & 1 \end{vmatrix}$$

- (ii) Three points $A(x_1, y_1)$, $B(x_2, y_2)$ and $C(x_3, y_3)$ are collinear iff area of $\Delta ABC = 0$.

- A square matrix A is called an orthogonal matrix if $AA' = AA' = I$.

- A square matrix A is called unitary if $AA^0 = A^0A = I$

- (i) The determinant of a unitary matrix is of modulus unity.

- (ii) If A is a unitary matrix then A', \bar{A}, A^0, A^{-1} are unitary.

- (iii) Product of two unitary matrices is unitary.

- Differentiation of Determinants :

Let $A = |C_1 C_2 C_3|$ is a determinant then

$$\frac{dA}{dx} = |C'_1 C_2 C_3| + |C_1 C'_2 C_3| + |C_1 C_2 C'_3|$$

Same process we have for row.

Thus, to differentiate a determinant, we differentiate one column (or row) at a time, keeping others unchanged.